

Short-Run Restrictions: An Identification Device?

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Motivation

- The econometrics of DSGE models has witnessed substantial advances over the recent years.
- Quite fashionable to bring DSGE models to the data.
 - Estimate deep parameters
 - Assess the relevance of propagation and amplification mechanisms
 - Conduct measures of fit

Motivation

- Variety of methods
 - Maximum Likelihood estimation (Altug, 1989, Ireland, 2004)
 - Generalized Method of Moments (Christiano and Eichenbaum, 1992, Burnside, Eichenbaum and Rebelo, 1993)
 - Bayesian techniques (Schorfheide, 2000, Smets and Wouters, 2003)
 - Minimum Distance Estimation (Rotemberg and Woodford, 1997, Christiano, Eichenbaum and Evans, 2005)
- This paper is concerned with the principles underlying the latest approach

Motivation

Minimum Distance Estimation

Estimate the structural parameters of DSGE models so as to minimize a weighted distance between

- IRF obtained from a Structural Vector AutoRegression (\widehat{IRF}) and
- theoretical IRF obtained from DSGE ($IRF(\theta)$).

$$\implies \theta \in \text{Argmin}_{\theta \in \Theta} \|IRF(\theta) - \widehat{IRF}\|_W$$

Motivation

3 main attractive features:

- 1 Bring structural and empirical approaches into closer conformity.
- 2 Set the focus only on those shocks that are relevant for the question under study
- 3 Not necessary to fully specify the whole stochastic structure of the DSGE model.

Motivation

- Key: Need to pin down the structural shocks, prior to estimating the DSGE parameters.
- Identification Restrictions to get IRFs
 - Long run restrictions (Blanchard and Quah (1989) and Galí (1999)) (close to most models)
 - Short-run Restrictions (Sims, 1980, Christiano, Eichenbaum, and Evans, 2005)

Motivation

Christiano, Eichenbaum and Vigfusson (2005):

- 1 SR performs better than LR restrictions.
- 2 SR restrictions correctly and precisely pin down the shocks.

Conjecture

SVARs with SR restrictions are a useful assessment device when constructing and evaluating a DSGE model.

Motivation

Key to this method:

DSGE and SVAR share the same restrictions (SR and/or LR)

- With SR, the DSGE and the VAR should share the same recursive structure
- Imposes some information restrictions on the observation of shocks
- Common intuition: This should affect the estimation

Motivation

- Empirically: This choice seems to be **innocuous!**
- Ex1: CEE (2005): Information sets restrictions have very little impact on the dynamic properties of their model in response to a money shock. (True in other monetary models)
- Ex2: CEV (2005): The response of hours to a permanent technology shock is left unaffected by observability restrictions.
- Very nice property!

This paper

- Is this always true? (Build an example to understand)
- When are parameters invariant to the short-run identification scheme used to identify shocks?
- Show how SR restrictions can be used to check identification

(A Tentative) Plan of the Talk

- The Minimum Distance Estimation with SR restrictions
- A fully fledged DSGE Model
- Estimate the model
- Assess the Role of Timing Restrictions
- Using timing restrictions to reveal identification problems
- Conclude

MDE with SR Restrictions

IRFs from the VAR

- Consider a sequence of data $\{x_t\}_{t=1}^T$, $x_t (n_x \times 1)$
- VAR representation

$$A(L)x_t = \varepsilon_t$$

where $A(L) = (I - A_1L - \dots - A_\ell L^\ell)$ and $\mathcal{E}\varepsilon_t = 0$ and $\mathcal{E}\{\varepsilon_t \varepsilon_t'\} = \Sigma$.

- Structural Shocks: $\varepsilon_t = S\eta_t$,
- VMA(∞) representation

$$x_t = C(L)\eta_t$$

where $C(L) = \sum_{i=0}^{\infty} C_i L^i = A(L)^{-1} S$.

MDE with SR Restrictions

IRFs from the VAR

- Short-run Restrictions:

$$S = C(0) = \begin{pmatrix} \times & 0 \\ \times & \times \end{pmatrix} \implies S = \text{chol}(\Sigma)$$

- Response of variable $x_{i,t}$ to shock j at horizon h :

$$l^{ij}(h) \equiv \frac{\partial x_{i,t+h}}{\partial \eta_{j,t}} = C_h^{(i,j)}$$

- $\hat{l}_T(\mathcal{H})$ denotes the vector collecting the IRFs from the SVAR for the horizons $\mathcal{H} = \{1, \dots, h\}$.

MDE with SR Restrictions

IRFs from the DSGE

- Generic linear(ized) DSGE model

$$\mathcal{E}_t^* \left\{ \sum_{i=-\tau_b}^{\tau_f} H_i(\theta_1) y_{t+i} + \sum_{i=-r_b}^{r_f} R_i(\theta_1) s_{t+i} \right\} = 0$$

θ_1 : vector of deep parameters, y_t : endogenous variables, s_t : forcing variables

- Expectations:

$$\mathcal{E}_t^*(F(y_i, s_j)) = \begin{bmatrix} \mathcal{E}\{F_1(y_i, s_j) | \mathcal{I}_{1,t}\} \\ \vdots \\ \mathcal{E}\{F_{n_y}(y_i, s_j) | \mathcal{I}_{n,t}\} \end{bmatrix}$$

where we place restrictions

MDE with SR Restrictions

IRFs from the DSGE

- Exogenous forcing variables

$$s_t = P(\theta_2) s_{t-1} + Q(\theta_2) \varepsilon_t,$$

θ_2 is a vector of parameters governing the dynamics of the forcing variables.

- Solution of the DSGE

$$y_t = D_1(\theta_1) y_{t-1} + \dots + D_{\tau_b}(\theta_1) y_{t-\tau_b} + M(\theta_1, \theta_2) s_t.$$

- IRFs: $I(\theta, \mathcal{H})$, where $\theta \equiv (\theta_1, \theta_2)$.

MDE with SR Restrictions

MDE Estimator

The MDE estimator of the structural parameters of the DSGE is

$$\hat{\theta}_T = \underset{\theta \in \Theta}{\operatorname{argmin}} (I(\theta, \mathcal{H}) - \hat{I}_T(\mathcal{H}))' W_T (I(\theta, \mathcal{H}) - \hat{I}_T(\mathcal{H})),$$

where W_T denotes the inverse of a consistent estimate of the covariance matrix of $\hat{I}_T(\mathcal{H})$

- Overidentification test (J-test)
- Distribution of $\hat{\theta}_T$: $\hat{\theta}_T \rightsquigarrow \mathcal{N}(0, V(\hat{\theta}_T))$ with

$$V(\hat{\theta}_T) = \left(\frac{\partial I(\theta, \mathcal{H})'}{\partial \theta} \Big|_{\theta = \hat{\theta}_T} W_T \frac{\partial I(\theta, \mathcal{H})}{\partial \theta'} \Big|_{\theta = \hat{\theta}_T} \right)^{-1}.$$

Where are we?

- The Minimum Distance Estimation with SR restrictions
- **A fully fledged DSGE Model**
- Estimate the model
- Assess the Role of Timing Restrictions
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A DSGE Model

- Account for output–hours dynamics
- Want an empirically relevant model
- Needs propagation mechanisms to allow for a (fair) formal test of the model.
- Introduce real frictions

A DSGE Model

The Household

- Standard!
- intertemporal expected utility function of the representative household

$$\mathcal{E} \left[\sum_{s=0}^{\infty} \beta^s \{ \log (C_{t+s} - bC_{t+s-1}) - \chi N_{t+s} \} \middle| \mathcal{I}_t \right]$$

A DSGE Model

Technology

- Standard Cobb–Douglas!

$$Y_t = K_t^\alpha (Z_t N_t)^{1-\alpha},$$

- Forcing variable

$$\log(Z_t) = \gamma_z + \log(Z_{t-1}) + \sigma_z \varepsilon_{z,t},$$

- Capital formation

$$K_{t+1} = (1 - \delta) K_t + \left[1 - \mathcal{S} \left(\frac{I_t}{I_{t-1}} \right) \right] I_t$$

A DSGE Model

2 versions of the Model

- ① \mathcal{M}_1 : **All** decisions are taken **after** the realization of the technology shock at t ($\mathcal{I}_t = \{Z_{t-i}; i = 0, \dots, \infty\}$).
- ② \mathcal{M}_2 : Follow CEV and assume that
 - ① Labor supply decisions are taken **prior to** observing the technology shock ($\mathcal{I}_t = \{Z_{t-i}; i = 1, \dots, \infty\}$).
 - ② Consumption and investment are however chosen **after** the shock is observed.

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Setting some parameters

- set $\{\alpha, \beta, \delta, \gamma_z\}$ to standard values

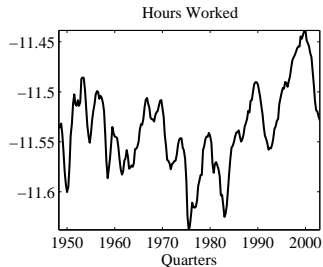
Baseline parametrization			
γ_z	α	δ	β
1.005	0.360	0.025	0.990

- Estimate parameters pertaining to dynamics (persistence, impact):

b (HP), ξ (IAC), σ_z (Std of Shock).

Which VAR?

- Run a VAR on growth rate of labor productivity in the nonfarm business-sector, and hours of all persons



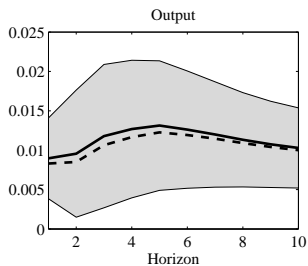
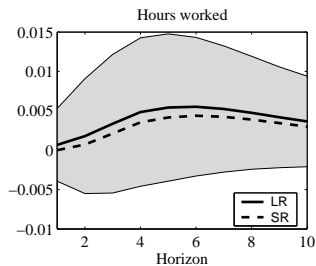
- 4 lags, Hours in levels (CEV)

Which IRF?

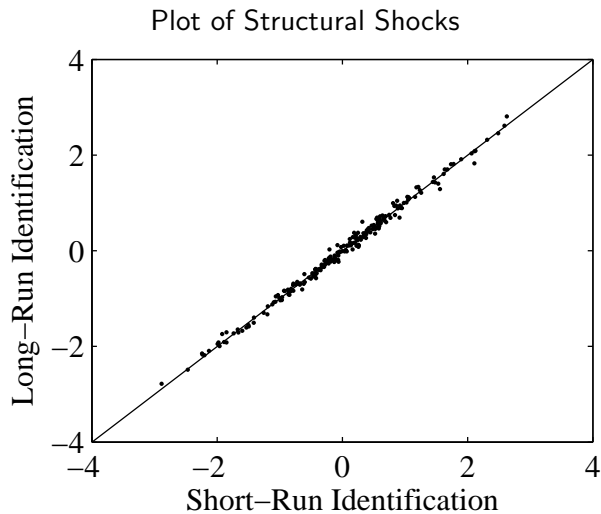
- Dynamics following the technology shock
- Standard to use LR restriction to get technology shocks
- We will use a short-run restriction!
- For this sample: observationally equivalent!!

Which IRF?

Impulse Response to a Technology Shock (Actual Data)



Which IRF?



Estimation

- To be matched: IRFs of y and h to the technology shock
- DSGE: model with information lags (model \mathcal{M}_2)
- 2 experiments
 - 1 RBC experiment: $\theta = (\sigma_z)$ and set $b = \xi = 0$
 - 2 Full model experiment: $\theta = (b, \xi, \sigma_z)$

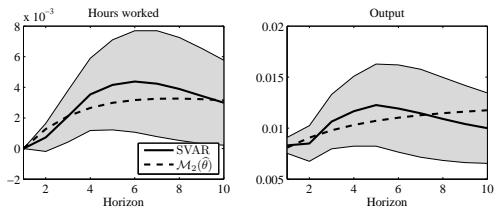
Estimation Results

	b	ξ	σ_z	J-stat
RBC Model	–	–	0.0102 (0.0004)	102.6938 [0.00]
Full Model	0.7253 (0.4337)	3.3942 (1.7215)	0.0126 (0.0006)	9.2817 [95.30]

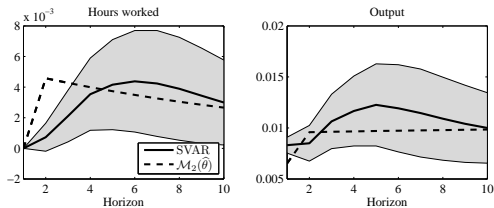
Note: Standard deviation into parenthesis, p-values (%) into brackets.

Fitting Properties

(a) Full Model



(b) RBC Model



- What have we done so far?
- Not much!
- But we have a model that provides a satisfactory representation of the data!
- The model can be taken as a good approximation of the DGP of the data
- Can work with it

Where are we?

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- **Assess the Role of Timing Restrictions**
- Using timing restrictions to reveal identification problems
- Conclude

Assessing the Role of Timing Restrictions

- Follow CEE (2005): Should the restrictions be innocuous, they should not alter the dynamics of the model!
- Compare IRFs from the unrestricted ($\mathcal{M}_1(\hat{\theta}_T)$) and the restricted ($\mathcal{M}_2(\hat{\theta}_T)$) versions of the IRFs

Assessing the Role of Timing Restrictions

Case 1: $\mathcal{M}_1(\hat{\theta}_T) = \mathcal{M}_2(\hat{\theta}_T)$

- Confirms CEE, CEV and other findings
- The method delivers the same estimated values of parameters for the 2 models
- Does not select a theory, just a way of identifying parameters.
- MDE treats fundamental parameters as deep parameters.

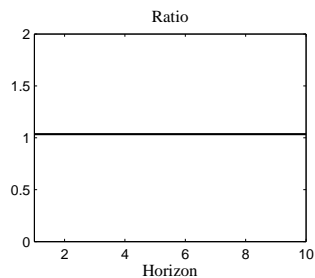
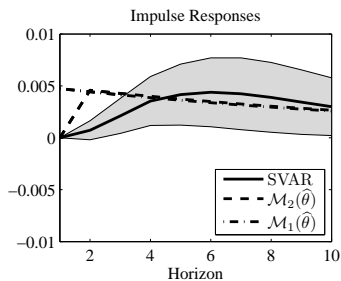
Assessing the Role of Timing Restrictions

Case 2: $\mathcal{M}_1(\hat{\theta}_T) \neq \mathcal{M}_2(\hat{\theta}_T)$

- SR restrictions have long-lasting effects
- Far from being innocuous: Identifies a theory
- Good news: SR are very informative
- Refute previous findings Estimation is sensitive to the decomposition.
- Need to be cautious

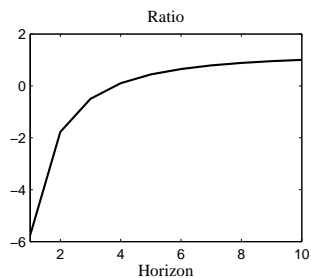
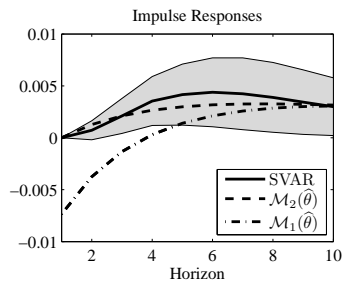
Assessing the Role of Timing Restrictions

The RBC version



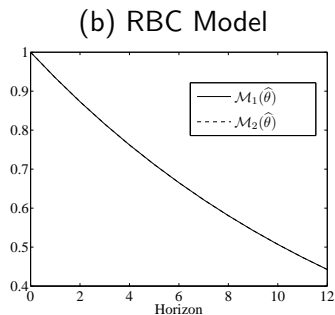
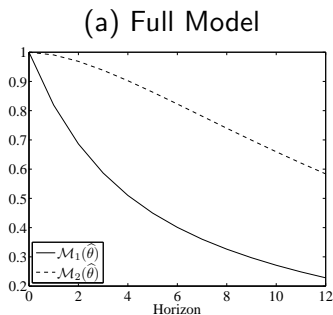
Assessing the Role of Timing Restrictions

The full version



Assessing the Role of Timing Restrictions

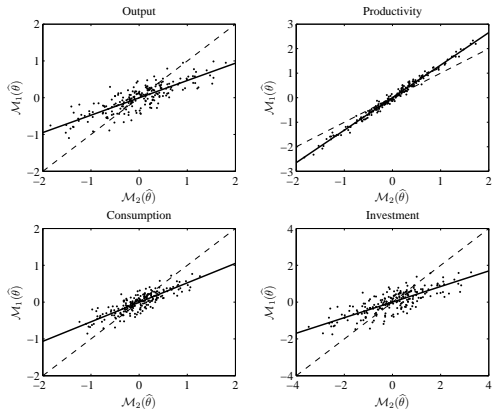
- Stems from the size of the propagation mechanisms in each version
- The full version propagates SR restrictions!
- This is confirmed by the autocorrelation function of the two models



Assessing the Role of Timing Restrictions

- Feed each model with the technology shocks identified by the VAR.
- Plot the series obtained from $\mathcal{M}_1(\hat{\theta}_T)$ against $\mathcal{M}_2(\hat{\theta}_T)$
- Illustrate how observationally equivalent (different) the two restriction sets are

Assessing the Role of Timing Restrictions

 $\mathcal{M}_1(\hat{\theta}_T)$ versus $\mathcal{M}_2(\hat{\theta}_T)$ 

Assessing the Role of Timing Restrictions

- Restricting the ability of agents to react to shocks actually puts a lot of structure on the data.
- Far from being innocuous.
- Provided the model possesses internal mechanisms.
- Imposing short-run restrictions on the VAR model amounts to selecting a theoretical model.
- Structure of information may matter for estimation.
- Is it useful?

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Counterfactuals

- Aim: Use SR restrictions to reveal identification problems
- Ask a very simple question:

Is it possible to replicate \mathcal{M}_2 with \mathcal{M}_1 ?

- Otherwise stated: Does there exist $\tilde{\theta}_T$ such that $\mathcal{M}_1(\tilde{\theta}_T) = \mathcal{M}_2(\hat{\theta}_T)$?
- If yes, do we have $\tilde{\theta}_T = \hat{\theta}_T$?

Counterfactuals

- Does there exist $\tilde{\theta}_T$ such that $\mathcal{M}_1(\tilde{\theta}_T) = \mathcal{M}_2(\hat{\theta}_T)$?
- Find $\tilde{\theta}_T$ so as to solve

$$\operatorname{argmin}_{\theta \in \Theta} \left(l_1(\theta, \mathcal{H}) - l_2(\hat{\theta}_T, \mathcal{H}) \right) \Omega_2(\hat{\theta}_T) \left(l_1(\theta, \mathcal{H}) - l_2(\hat{\theta}_T, \mathcal{H}) \right)'$$

$l_j(\theta, \mathcal{H})$ are IRFS for model j , and

$$\Omega_2(\hat{\theta}_T) = \left(\frac{\partial l_2(\theta, \mathcal{H})'}{\partial \theta} \Big|_{\theta=\hat{\theta}_T} V(\hat{\theta}_T) \frac{\partial l_2(\theta, \mathcal{H})}{\partial \theta'} \Big|_{\theta=\hat{\theta}_T} \right)^{-1}.$$

- Over-identification test for the equivalence between models (with $nh - \dim(\theta)$ d.f.)

Counterfactuals

- If no then SR restriction really matter,
- If yes: do we have $\tilde{\theta}_T = \hat{\theta}_T$?
- Can be tested by

$$\mathcal{W}_1(\tilde{\theta}_T, \hat{\theta}_T) = (\tilde{\theta}_T - \hat{\theta}_T)' V(\hat{\theta}_T)^{-1} (\tilde{\theta}_T - \hat{\theta}_T)$$

which is χ^2 with $\dim(\theta)$ d.f.

- If yes, SR restrictions do not matter (RBC model)
- If no, use it further.

Counterfactuals

	ξ	b	σ_z	J-stat	$\mathcal{W}_1(\tilde{\theta}_T, \hat{\theta}_T)$
Benchmark	3.3942	0.7253	0.0126		
Output	0.9750 (0.3996)	-0.0404 (0.0929)	0.0124 (3.4541e-4)	0.1479 [100.00]	6.8710 [7.60]
Productivity	1.0566 (0.6757)	-0.1101 (0.1778)	0.0130 (3.6125e-4)	0.2373 [99.99]	8.0250 [4.50]
Consumption	1.3330 (3.5999)	0.4950 (0.5748)	0.0128 (9.0620e-4)	0.04392 [100.00]	2.9478 [39.90]
Investment	0.2875 (0.9353)	0.9855 (0.0540)	0.0225 (0.0422)	0.0677 [100.00]	616.5846 [0.00]
All	1.4061 (0.2972)	-0.0414 (0.0770)	0.0127 (1.4832e-4)	5.73815 [100.00]	5.7266 [12.60]

Note: Standard deviation into parenthesis, p-values (%) into brackets.

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Counterfactuals

Going further

- Assume $\tilde{\theta}_T \neq \hat{\theta}_T$
- Feed model \mathcal{M}_2 with $\tilde{\theta}_T$
- Is the restricted model \mathcal{M}_2 affected by this change of parameters?
- Formal test

$$\mathcal{W}_2(\tilde{\theta}_T, \hat{\theta}_T) = \left(l_2(\tilde{\theta}_T, \mathcal{H}) - l_2(\hat{\theta}_T, \mathcal{H}) \right) \Omega_2(\hat{\theta}_T) \left(l_2(\tilde{\theta}_T, \mathcal{H}) - l_2(\hat{\theta}_T, \mathcal{H}) \right)'$$

- If one cannot reject the null: Severe identification problem!

Counterfactuals

Going further

- Applying the test

$$\mathcal{W}_2(\tilde{\theta}_T, \hat{\theta}_T)$$

Output	Productivity	Consumption	Investment
1.5570	1.6873	0.1736	56.9746
[99.67]	[99.55]	[99.99]	[0.00]

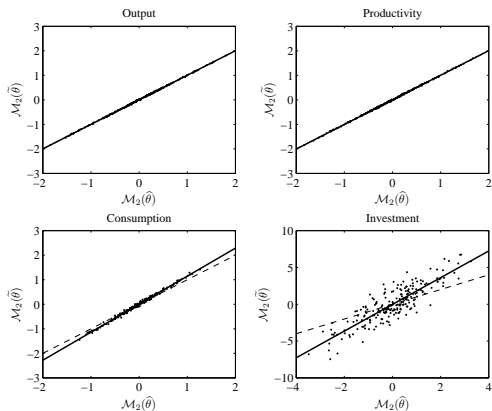
Note: p-values (%) into brackets.

- Very bad news!
- $\mathcal{M}_2(\tilde{\theta}_T)$ and $\mathcal{M}_2(\hat{\theta}_T)$ share the same dynamic properties.
- Identification problem!

Counterfactuals

Going further

$$\mathcal{M}_2(\hat{\theta}_T) \text{ versus } \mathcal{M}_2(\tilde{\theta}_T)$$



Concluding Remarks

- This paper investigates the quantitative implications of restricting the information sets conditional on which decisions are taken in DSGE models.
- Propose a variety of simple statistical tools designed to assess the role of timing restrictions on aggregate dynamics.
- Use them on a fully-fledged DSGE model which we formally take to US data.

Concluding Remarks

- Our results indicate that restricting the information set is of
 - No substantial consequences if one is dealing with a version of our DSGE model with weak internal propagation mechanisms
 - Big consequences when the model possesses strong propagation mechanisms
- Illustrates how to use these restrictions to reveal identification problems.