

# *Estimating Macroeconomic Models: A Likelihood Approach*

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# Outline

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- We apply **particle filtering** to evaluate the likelihood of the model.
- We estimate a neoclassical business cycle model with investment-specific technological change and stochastic volatility.

## What is the Particle Filter?

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- Alternatives? Problems?

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- We want to track conditional density  $p(S_t | y^{t-1}; \gamma)$ .

## Factorization of the Likelihood

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- Why?

$$\begin{aligned} p(y^T; \gamma) &= \prod_{t=1}^T p(y_t | y^{t-1}; \gamma) \\ &= \prod_{t=1}^T \int p(y_t | S_t; \gamma) p(S_t | y^{t-1}; \gamma) dS_t \end{aligned}$$

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- Knowledge of  $\{p(S_t | y^{t-1}; \gamma)\}_{t=1}^T$  allows the evaluation of the likelihood of the model.

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$$p(y^T; \gamma) \simeq \prod_{t=1}^T \frac{1}{N} \sum_{i=1}^N p(y_t | s_{t|t-1}^i; \gamma)$$

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Evaluating the likelihood function  $\Leftrightarrow$  Drawing from density:

$$\left\{ p(S_t | y^{t-1}; \gamma) \right\}_{t=1}^T$$

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### 2. Update: Bayes' theorem

$$p(S_t|y^t; \gamma) = \frac{p(y_t|S_t; \gamma) p(S_t|y^{t-1}; \gamma)}{p(y_t|y^{t-1}; \gamma)}$$

where:

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1. **Forecast:** Using a draw from  $p(S_{t-1}|y^{t-1}; \gamma)$ ,  $p(W_t; \gamma)$ , and  $S_t = f(S_{t-1}, W_t; \gamma)$  we get a draw  $p(S_t|y^{t-1}; \gamma)$ .

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2. **Update:** How do we draw from  $p(S_t|y^t; \gamma)$  using draws from  $p(S_t|y^{t-1}; \gamma)$ ?

## Some Notation

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- $\left\{ s_{t-1|t-1}^i \right\}_{i=1}^N$   $N$  i.i.d. draws from  $p(S_{t-1}|y^{t-1}; \gamma)$ .

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- Weights of draws  $\left\{ s_{t|t-1}^i \right\}_{i=1}^N$  :

$$q_t^i = \frac{p \left( y_t | s_{t|t-1}^i; \gamma \right)}{\sum_{i=1}^N p \left( y_t | s_{t|t-1}^i; \gamma \right)}$$

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- Then,  $\left\{\tilde{s}_t^i\right\}_{i=1}^N$  is a draw from  $p\left(S_t|y^t;\gamma\right)$ :

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- Then,  $\left\{\tilde{s}_t^i\right\}_{i=1}^N$  is a draw from  $p\left(S_t|y^t;\gamma\right)$ :

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- Proof: Importance sampling and Bayes' theorem.

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1. **Forecast:** We can use a draw  $\left\{s_{t|t}^i\right\}_{i=1}^N$  from  $p\left(S_t|y^t; \gamma\right)$ , a draw from  $p\left(W_{t+1}; \gamma\right)$ , and  $S_{t+1} = f\left(S_t, W_{t+1}; \gamma\right)$  to get a draw  $\left\{s_{t+1|t}^i\right\}_{i=1}^N$ .

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2. **Update:** Using the proposition, we can use a draw  $\left\{s_{t|t-1}^i\right\}_{i=1}^N$  from  $p\left(S_t|y^{t-1}; \gamma\right)$  to get a draw  $\left\{s_{t|t}^i\right\}_{i=1}^N$  from  $p\left(S_t|y^t; \gamma\right)$ .

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**Step 3, Update:** Draw  $\left\{s_{t|t}^i\right\}_{i=1}^N$  with replacement from  $\left\{s_{t|t-1}^i\right\}_{i=1}^N$  with probabilities  $\left\{q_t^i\right\}_{i=1}^N$ . If  $t < T$  set  $t \rightsquigarrow t + 1$  and go to step 1. Otherwise stop.

## Particle Filtering II

Use  $\left\{ \left\{ s_{t|t-1}^i \right\}_{i=1}^N \right\}_{t=1}^T$  to compute:

$$p(y^T; \gamma) \simeq \prod_{t=1}^T \frac{1}{N} \sum_{i=1}^N p(y_t | s_{t|t-1}^i; \gamma)$$

We can filter, forecast, and smooth

## An Application: a Business Cycle Model

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- I want to show the power of the particle filter.

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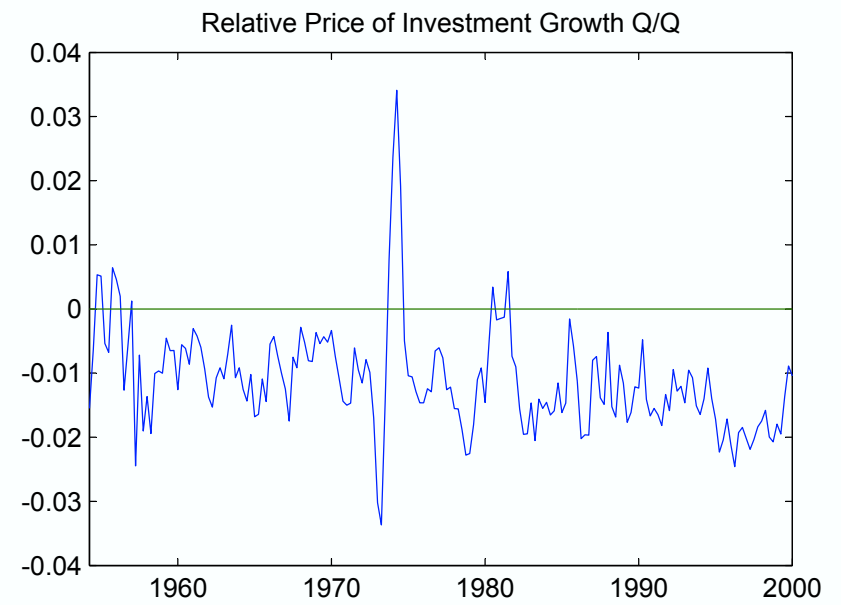
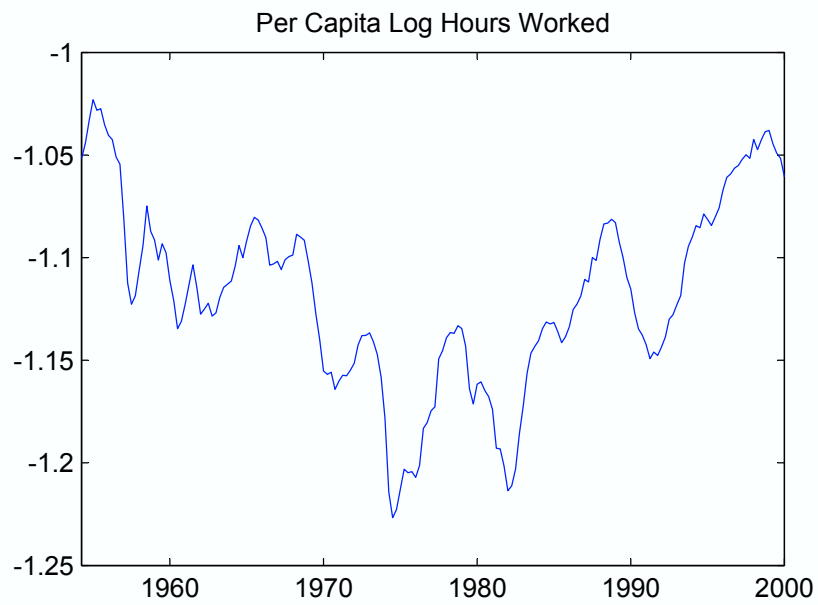
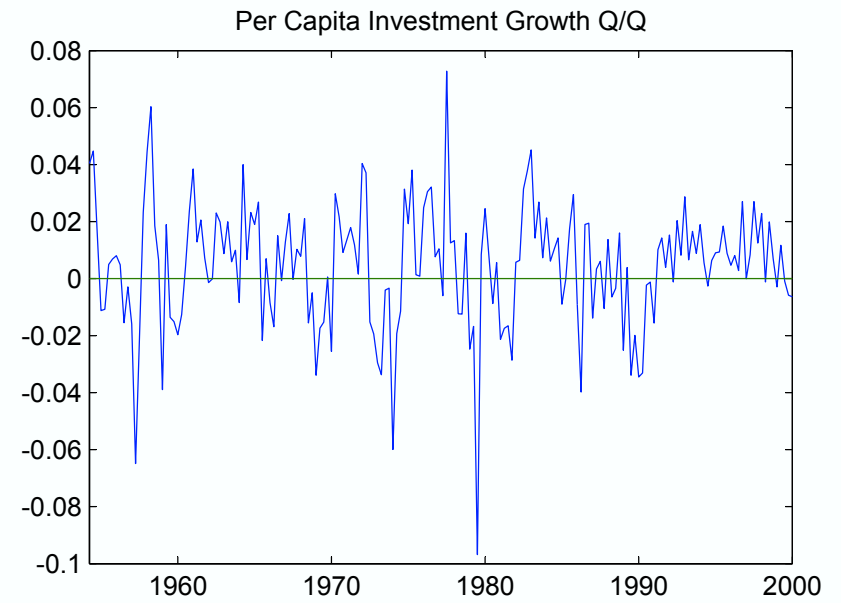
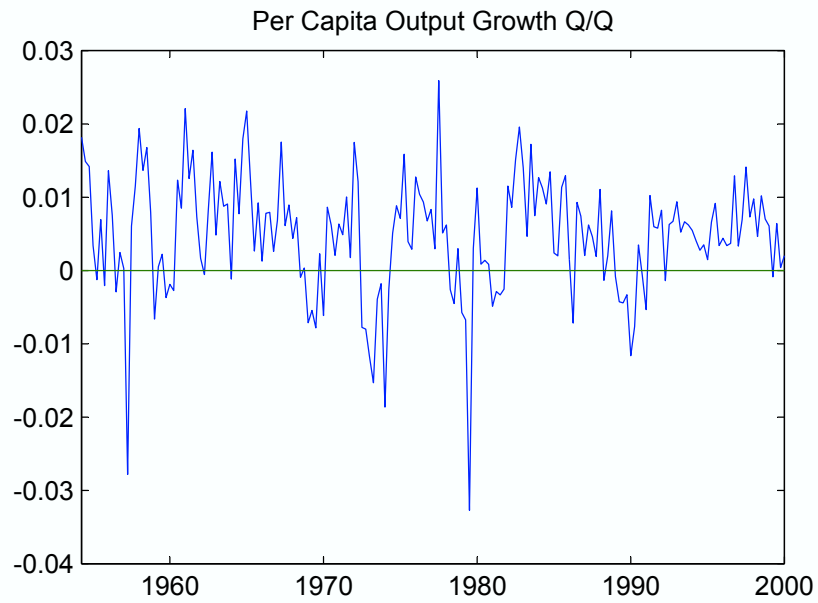
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- A business cycle model with:
  1. Investment-specific technological change. Greenwood, Hercowitz, and Krusell (1997 and 2000)
  2. Stochastic volatility.



## Environment

- Representative household with utility function:

$$E_0 \sum_{t=0}^{\infty} \beta^t \left( e^{d_t} \log C_t + \psi \log (1 - L_t) \right)$$

- Final Good:  $C_t + X_t = A_t K_t^\alpha L_t^{1-\alpha}$
- Law of motion of capital:  $K_{t+1} = (1 - \delta) K_t + V_t X_t$
- Shocks:

$$d_t = \rho d_{t-1} + \sigma_{dt} \varepsilon_{dt}, \quad \varepsilon_{dt} \sim \mathcal{N}(0, 1)$$

$$\log A_t = \gamma + \log A_{t-1} + \sigma_{at} \varepsilon_{at}, \quad \gamma \geq 0 \text{ and } \varepsilon_{at} \sim \mathcal{N}(0, 1)$$

$$\log V_t = v + \log V_{t-1} + \sigma_{vt} \varepsilon_{vt}, \quad v \geq 0 \text{ and } \varepsilon_{vt} \sim \mathcal{N}(0, 1)$$

# Stochastic Volatility

We follow a standard specification:

$$\log \sigma_{dt} = (1 - \lambda_d) \log \bar{\sigma}_d + \lambda_d \log \sigma_{dt-1} + \tau_d \eta_{dt} \text{ and } \eta_{dt} \sim \mathcal{N}(0, 1)$$

$$\log \sigma_{at} = (1 - \lambda_a) \log \bar{\sigma}_a + \lambda_a \log \sigma_{at-1} + \tau_a \eta_{at} \text{ and } \eta_{at} \sim \mathcal{N}(0, 1)$$

$$\log \sigma_{vt} = (1 - \lambda_v) \log \bar{\sigma}_v + \lambda_v \log \sigma_{vt-1} + \tau_v \eta_{vt} \text{ and } \eta_{vt} \sim \mathcal{N}(0, 1)$$

## Performing Likelihood-Based Inference

- We compute the model using a perturbation method.
- Time series:
  1. Relative price of capital, output, investment, and hours.
  2. Sample: 1955:Q1 to 2000:Q4.

- Vector of parameters  $\gamma$  is:

$$(\rho, \beta, \psi, \alpha, \delta, \nu, \zeta, \tau_d, \tau_a, \tau_v, \bar{\sigma}_d, \bar{\sigma}_a, \bar{\sigma}_v, \lambda_a, \lambda_v, \lambda_d, \sigma_1^\epsilon, \sigma_2^\epsilon, \sigma_3^\epsilon)$$

- Use a **Random-walk Metropolis-Hastings** to explore the likelihood: Classical and Bayesian.

Table 5.1: Maximum Likelihood Estimates

Parameter	Point Estimate	Standard Error ( $\times 10^{-3}$ )
$\rho$	0.967	3.743
$\beta$	0.999	0.460
$\psi$	2.343	6.825
$\nu$	8.960E-003	0.828
$\zeta$	3.594E-005	2.254
$\tau_a$	7.120E-002	1.589
$\tau_\nu$	7.772E-003	2.940
$\tau_d$	5.653E-002	2.034
$\bar{\sigma}_a$	4.008E-004	0.692
$\bar{\sigma}_\nu$	8.523E-003	0.101
$\bar{\sigma}_d$	5.016E-003	2.344
$\lambda_a$	4.460E-002	6.788
$\lambda_\nu$	0.998	8.248
$\lambda_d$	0.998	2.302
$\sigma_{1\epsilon}$	1.031E-005	0.424
$\sigma_{2\epsilon}$	1.024E-004	0.495
$\sigma_{3\epsilon}$	1.110E-005	0.082

Figure 6.1: Model versus Data

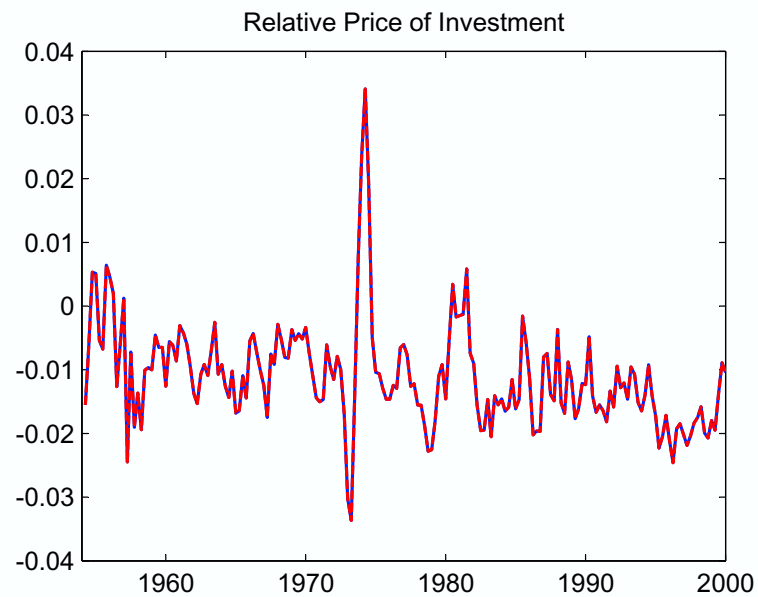
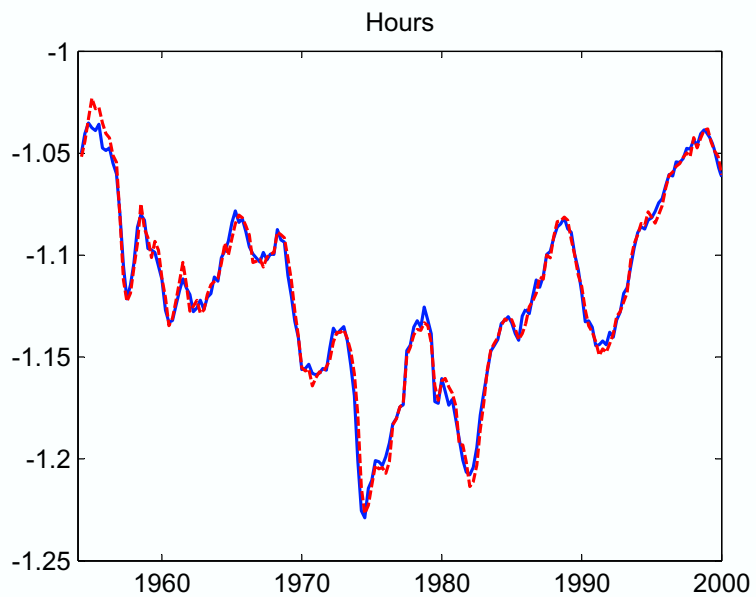
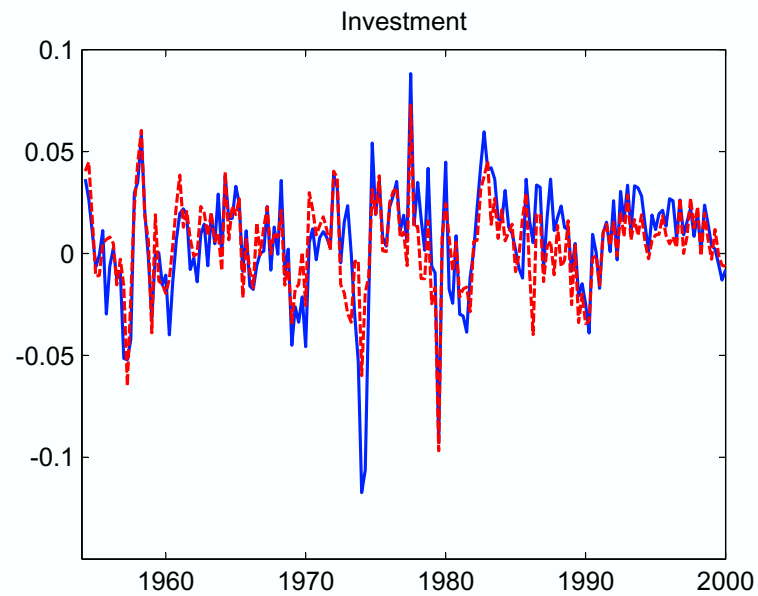
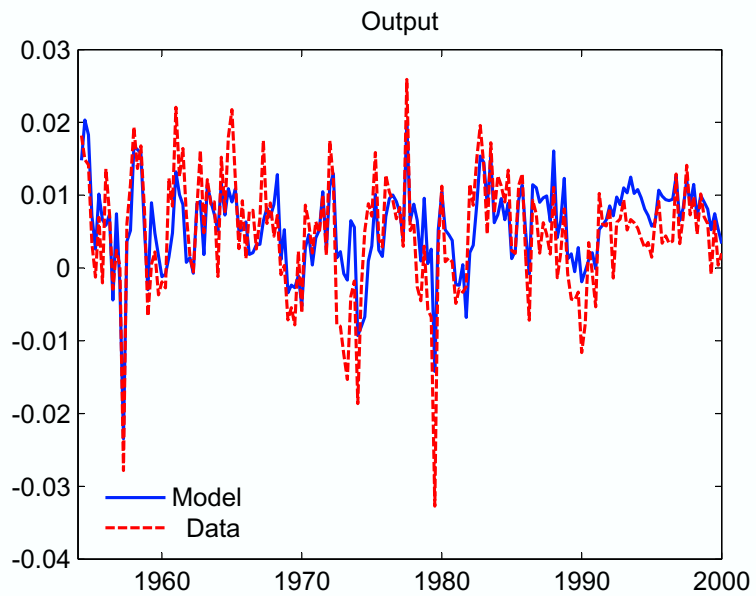


Figure 6.2: Smoothed Capital and Shocks

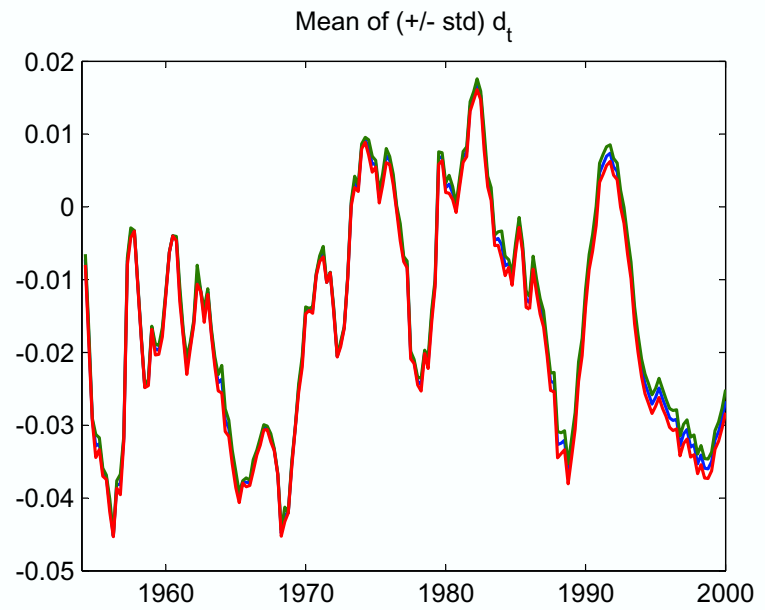
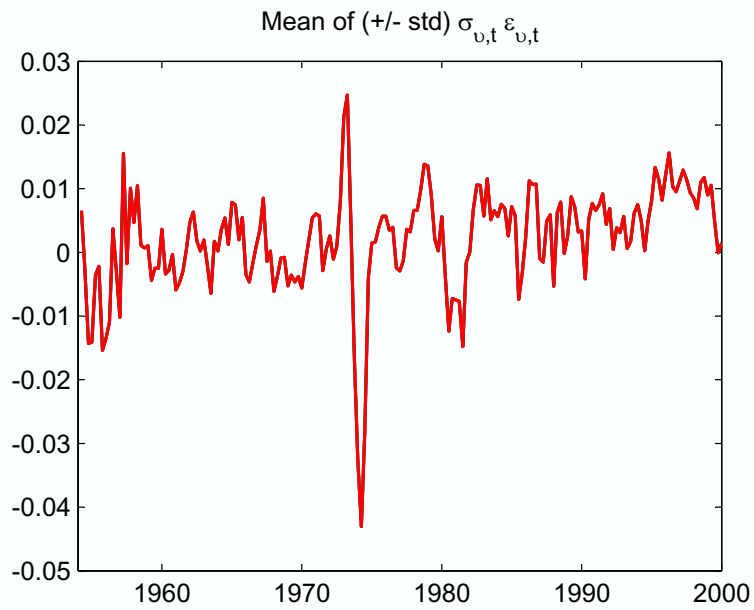
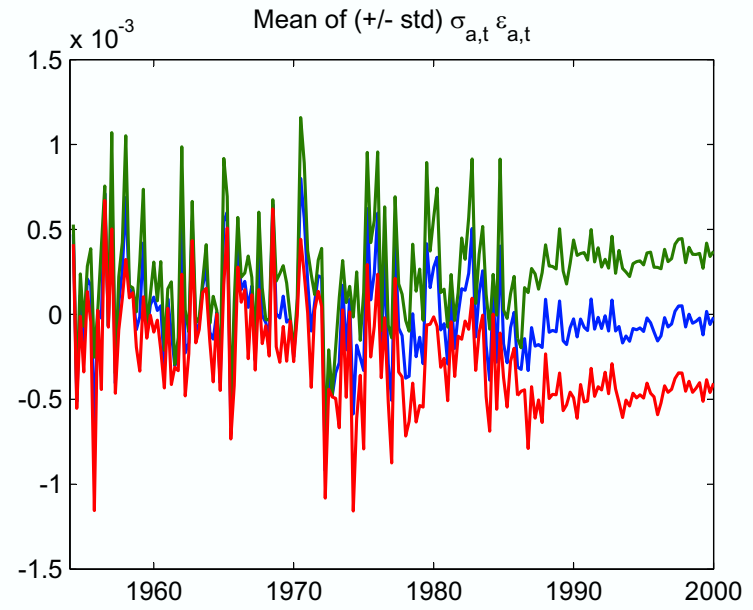
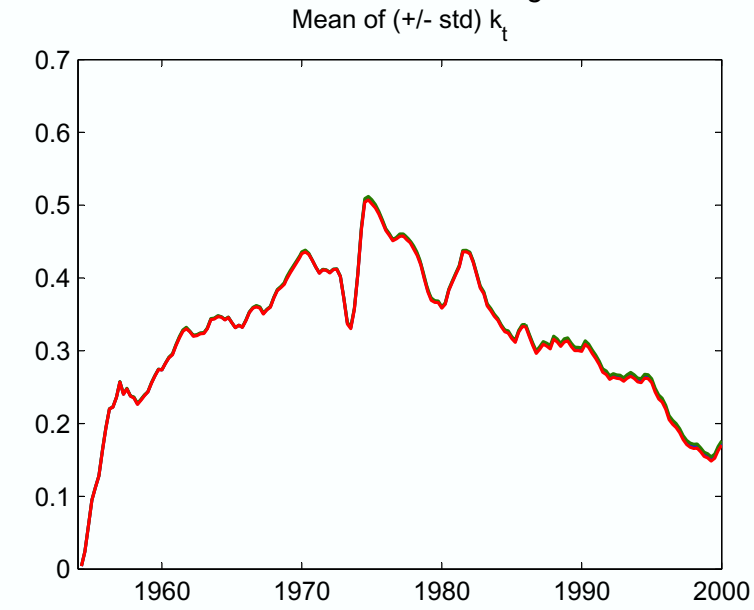


Figure 6.3: Smoothed Volatilities

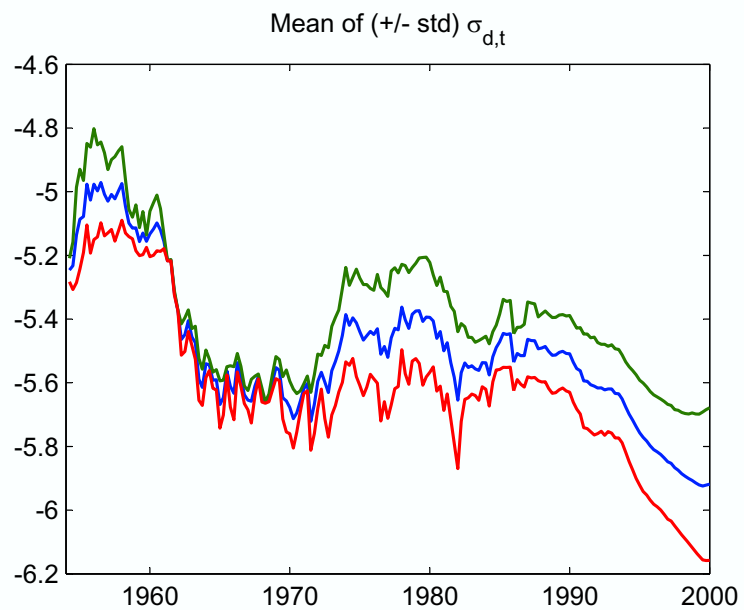
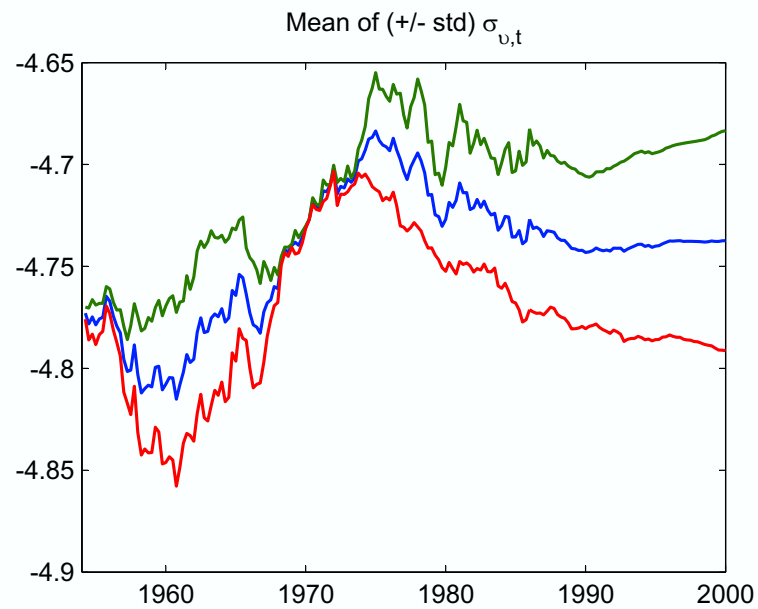
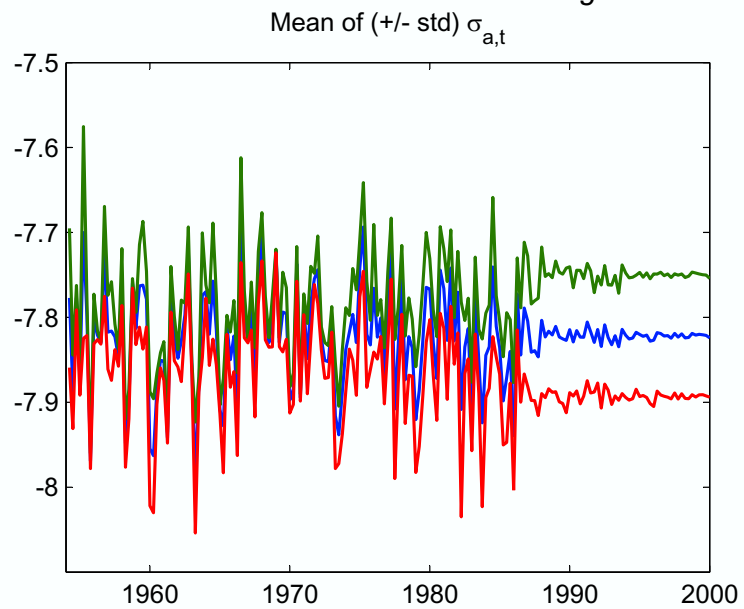


Figure 6.4: Instantaneous Standard Deviation

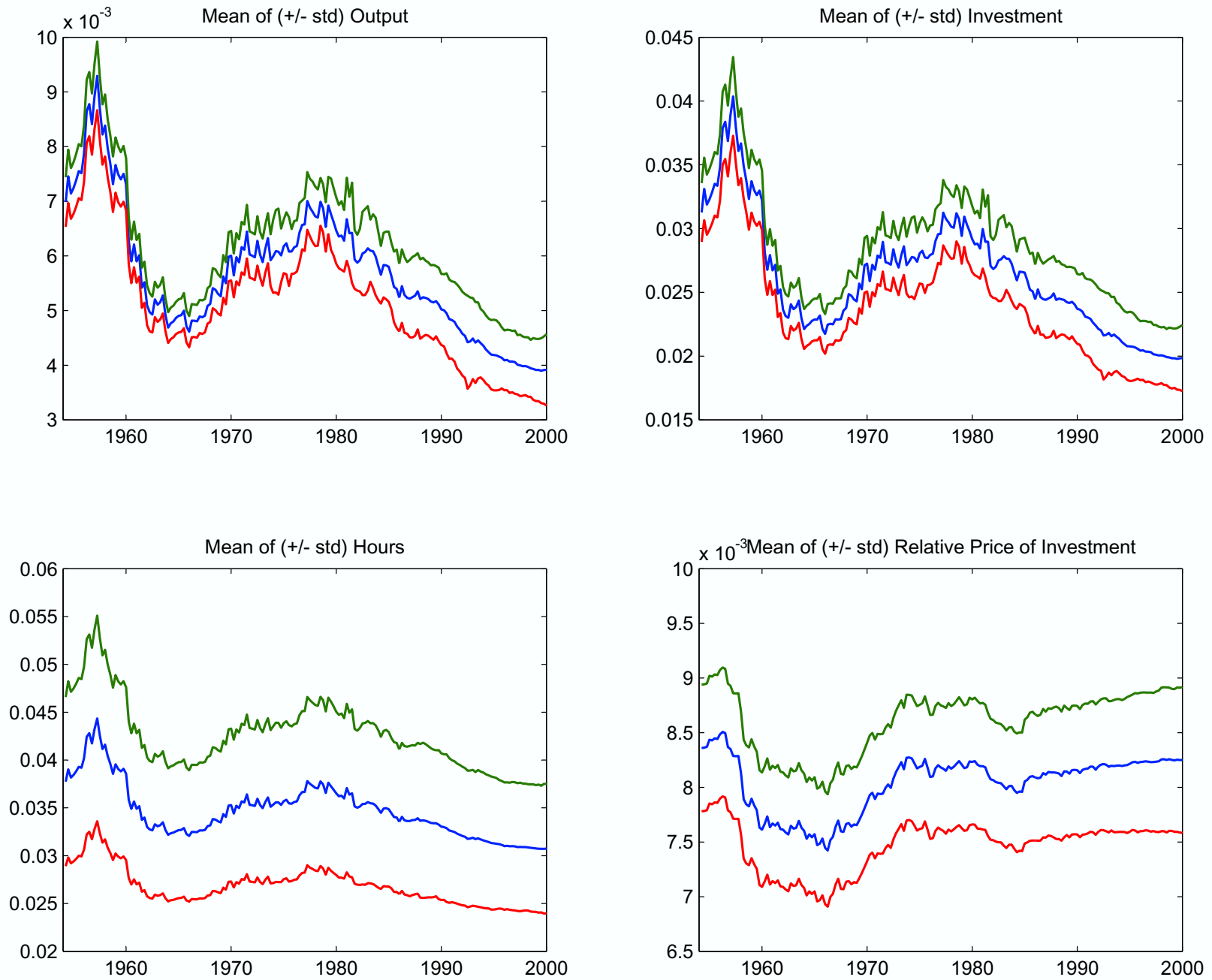


Figure 6.5: Counterfactual Exercise 1

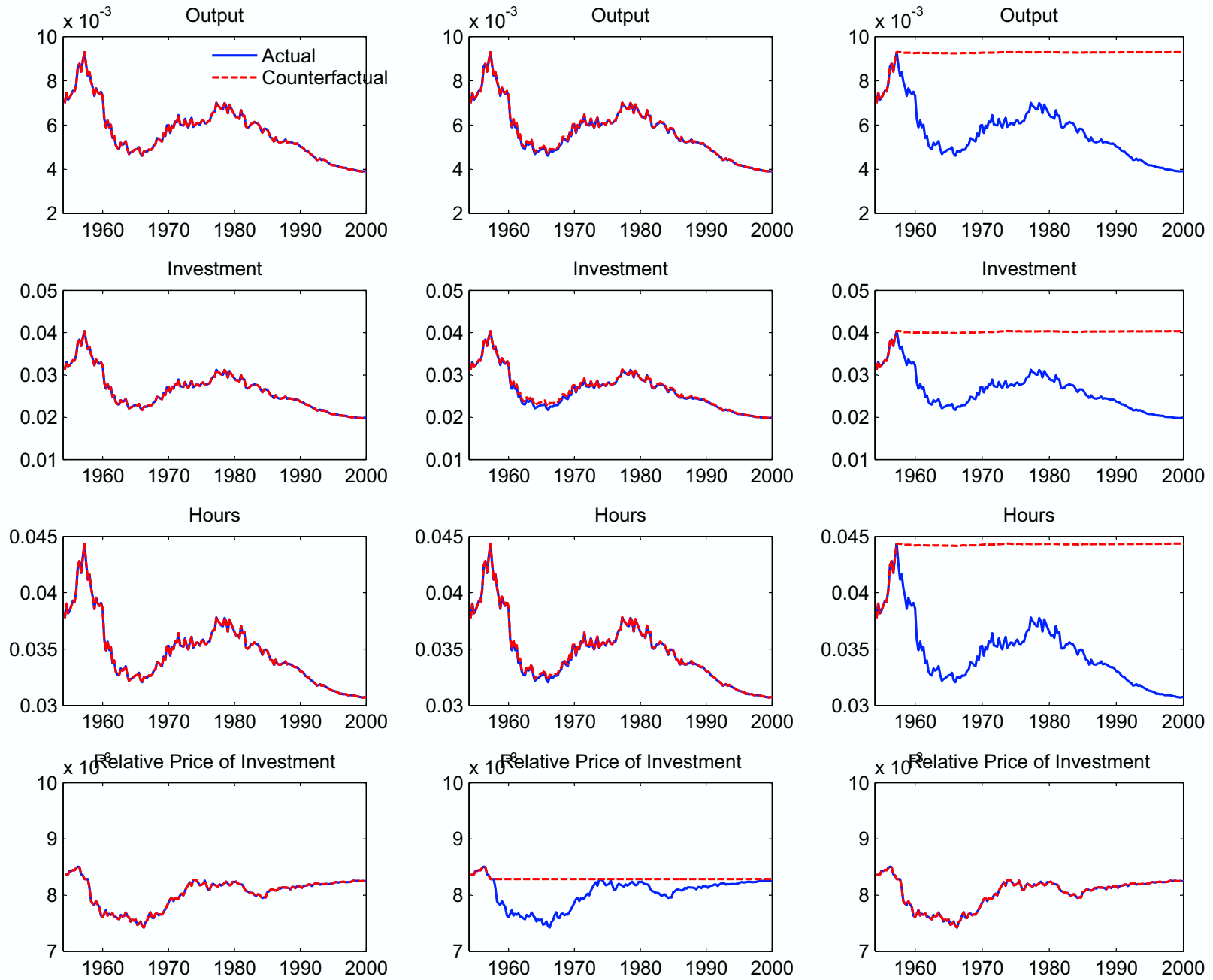


Figure 6.6: Counterfactual Exercise 2

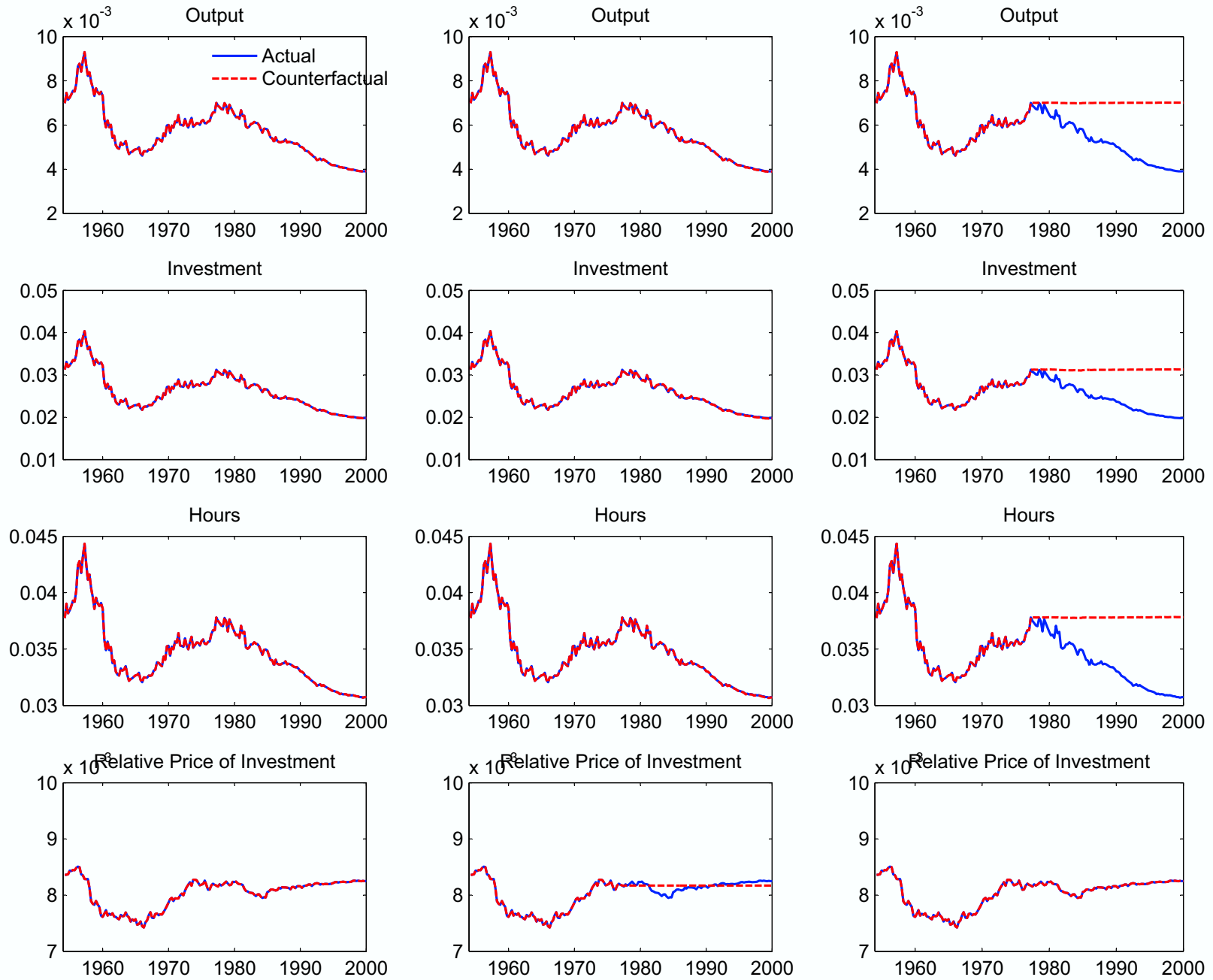
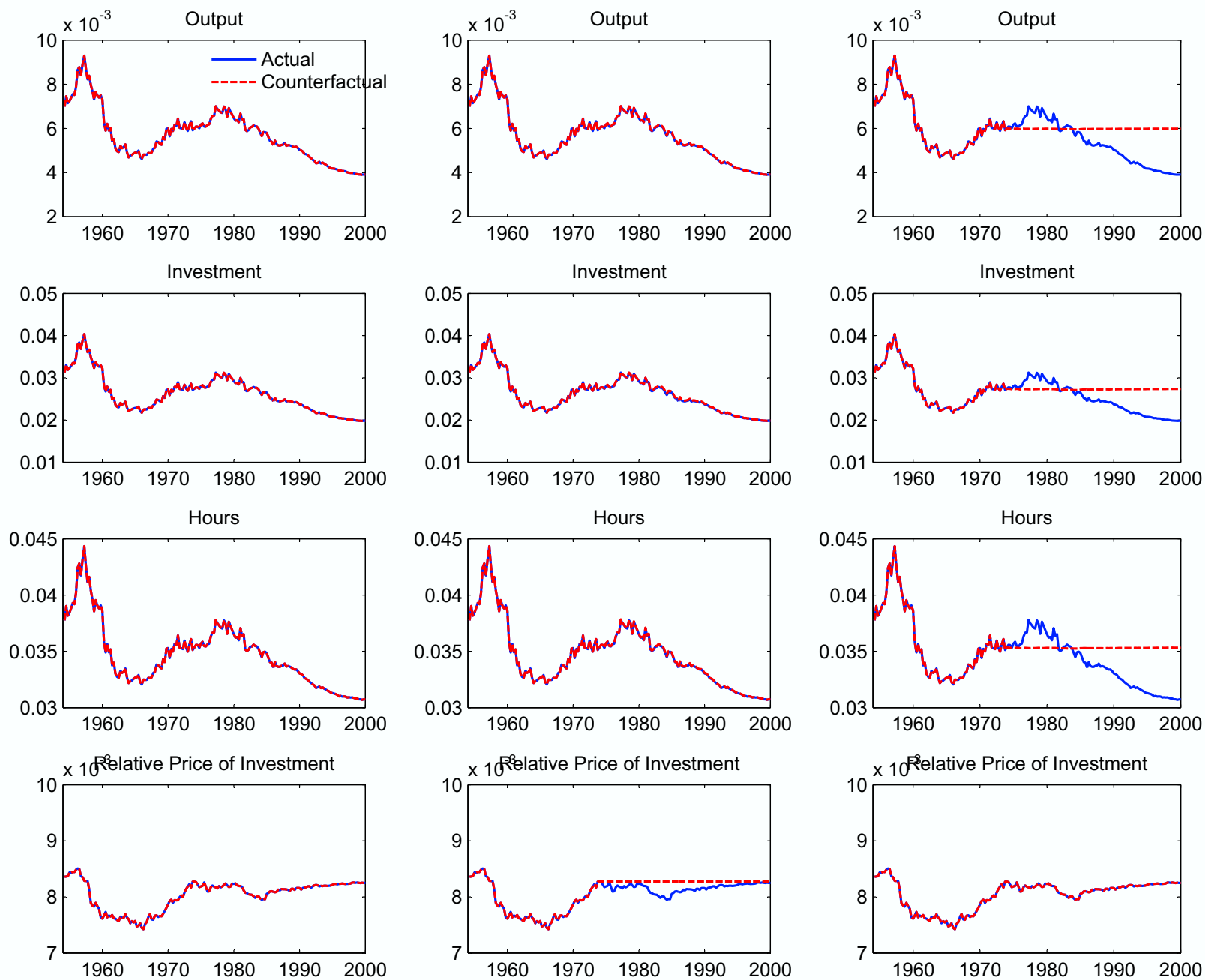


Figure 6.7: Counterfactual Exercise 3



# Are Nonlinearities and Non-normalities Important?

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- We estimate four version of the model:

Table 7.1: Versions of the Model

Solution	No Stochastic Volatility	Stochastic Volatility
Linear	Version 1	Version 2
Quadratic	Version 3	Benchmark

## Are Nonlinearities and Non-normalities Important?

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- We use Likelihood Ratio tests to compare models, **Rivers and Vuong (2002)**.
- Loglike benchmark: **2350.6**, loglike version 2: **2230.4**

Figure 7.1: Comparison of Smoothed Capital and Shocks

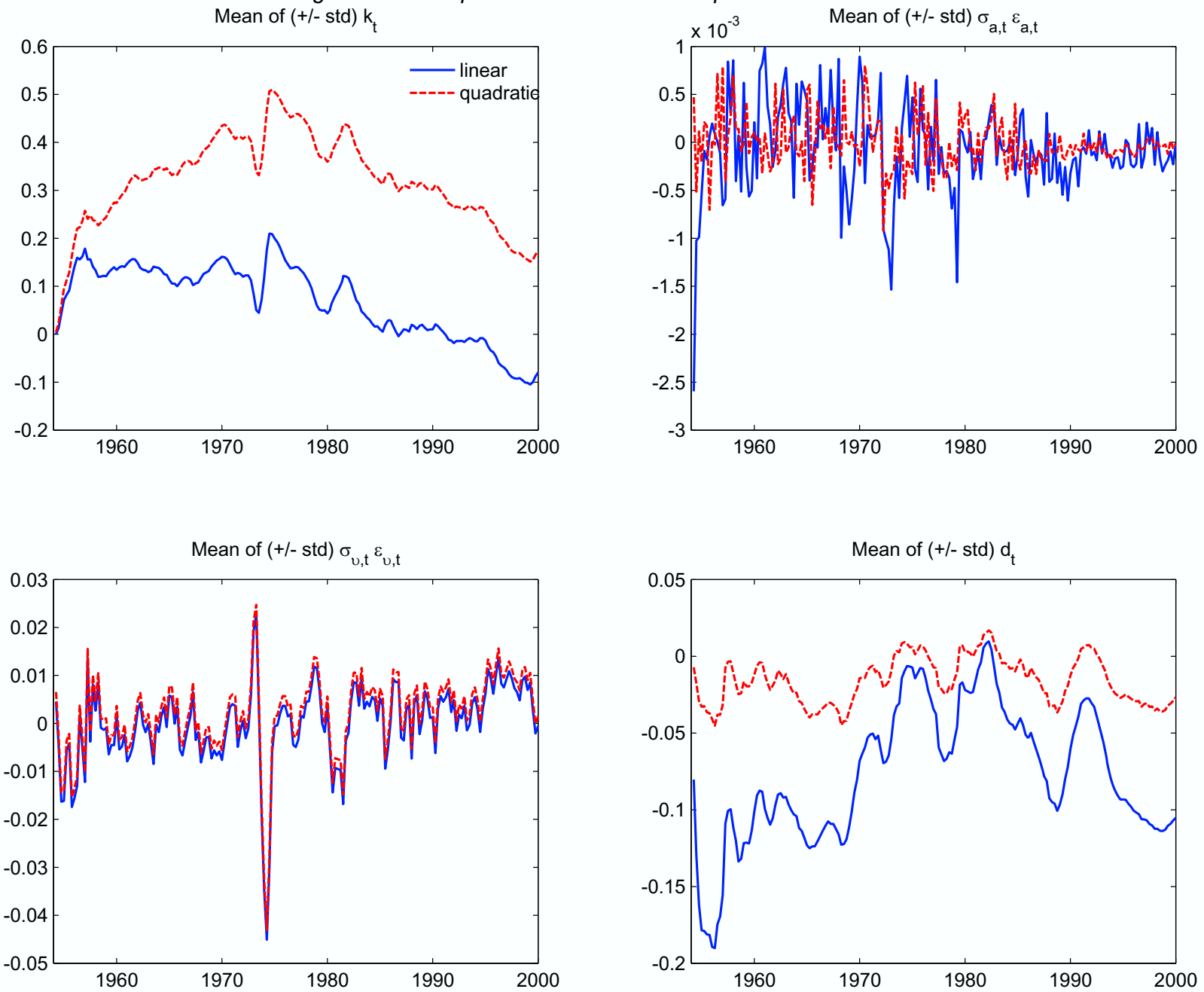
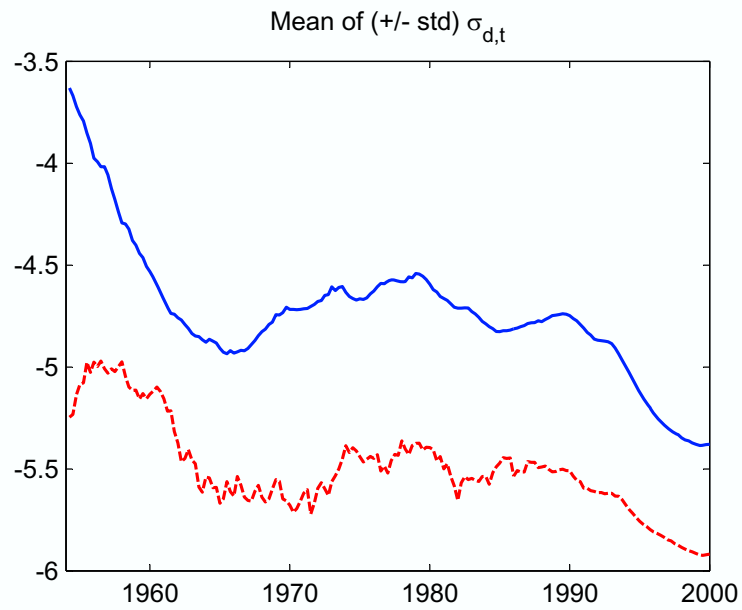
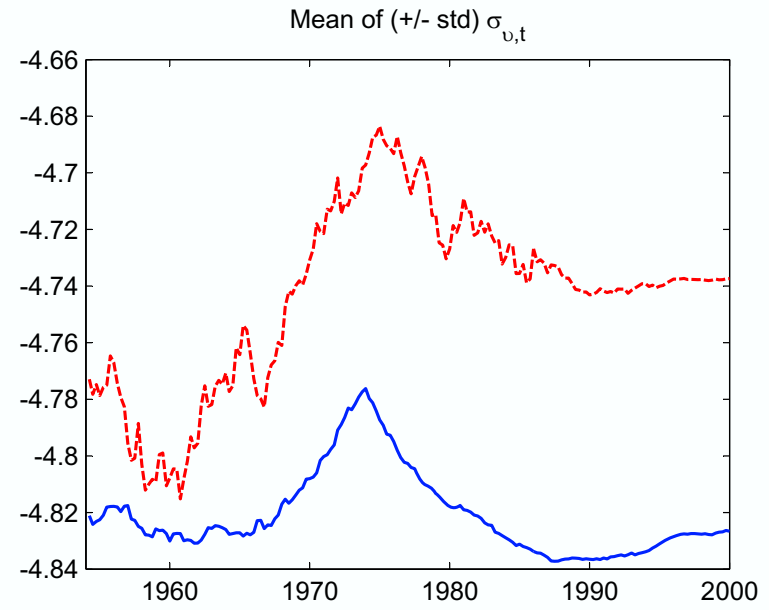
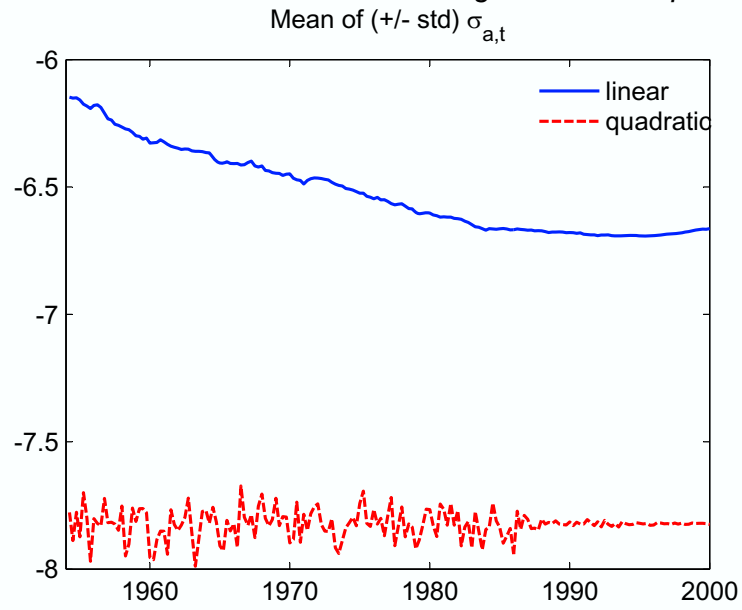


Figure 7.2: Comparison of Smoothed Volatilities



## Conclusions

1. Particle filtering is a general purpose and efficient method to estimate DSGE models.
2. We learned about the importance of stochastic volatility to account for U.S. Business Cycle.
3. Much exciting work to do in the next few years!